

# Actuation of MEMS Devices using Radiation Pressure

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# Acknowledgements

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Research Council
- CRC – Canada Research Chairs Program

# MEMS Activities in Canada

- Optics and Photonics
- RF, Microwave, and Telecommunication Applications
- Micromachining Technologies and Facilities
- Microfluidics (Biomedical, Chemical Sensor Systems, Micro Test Analysis Systems)
- Sensors, Actuators, and Microrobotics
- CAD, Modeling, and Simulation
- Testing and Test Structures

Source: CMC – Canadian Manufacturing Corporation

# MEMS Activities in Canada

## Universities

- Simon Fraser University (BC)
- University of Alberta (AB)
- University of Calgary (AB)
- University of Saskatchewan (SK)
- University of Manitoba (MB)
- Carleton University (ON)
- **McMaster University (ON)**
- Queen's University (ON)
- University of Toronto (ON)
- University of Waterloo (ON)
- University of Western Ontario (ON)
- University of Windsor (ON)
- Concordia University (QC)
- École Polytechnique de Montréal (QC)
- McGill University (QC)
- Dalhousie University (NS)

## National Labs and Consortia

- Canadian Manufacturing Corporation
- Communications Research Centre
- INO, Photonic Materials and Processes
- National Research Council / Institute for Microstructural Sciences
- Photonics Research Ontario

## Corporations

- Bookham Technology
- Centre for Large Space Structures and Systems CLS3 Inc.
- COM DEV Ltd., R&D department
- DALSA Semiconductor
- Infolytica Corporation
- Integrated Engineering Software Sales Inc.
- i-STAT Corp
- JDS Uniphase Corporation, R&D (Strategic Research)
- Medtronic of Canada Limited
- Micralyne Inc.
- Optenia
- SUSS MicroTec, Inc.
- Umech Technologies, LLC
- Xerox Research of Canada

Source: CMC – Canadian  
Manufacturing Corporation

# MEMS Activities at McMaster

- Radiation pressure experiments (1)
- Ultra-low-force Sensor development (1)
- MEMS integrated optics (2)
- III-V MEMS devices and systems (1)
- Adaptive Optics (1)
- Laser micromachining for new materials (2)
- “nanopower” for ubiquitous sensing (1)
- Communication to ubiquitous sensors (2)
- Novel microfluidic applications (2)
- Biomedical applications (3)

CEMD – Research Fabrication facility

BIMR – Materials and Characterization

HHS – Medical School and research on campus

Motivation

Background:

- history of radiation pressure experiments
- laser tweezer experiments

Radiation pressure vs. thermal effects

Measurement system/Experimental design

Measurement theory/Circuitry

Present Data

Conclusions

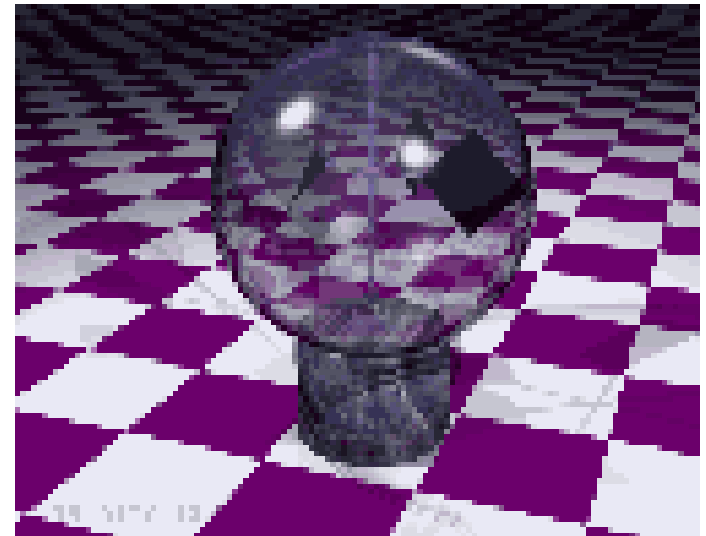
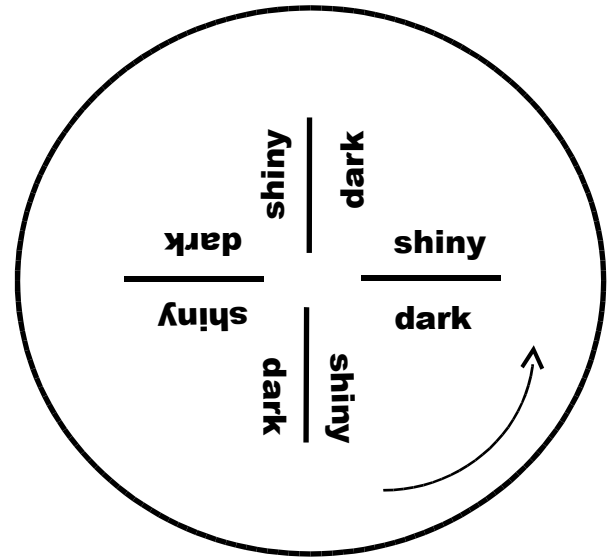
# Motivation

- Connection to optical tweezer experiments
- Understand role of radiation pressure in Optical MEMS devices
- Study physics of Casimir effect using real photons instead of virtual ones – allows the effects to be controlled and studied, including spectroscopically
- Study and utilize plasmon effects to generate enhanced forces on MEMS devices
- Framework for implementing optical computing
- Framework for studying macroscopic quantum entanglement

# Radiation Pressure Experiments

A brief history of radiation pressure experiments:

- 1864 - Maxwell, **pressure on reflection =  $2I/c$**
- 1873 - Sir William Crookes - “Crookes’s Radiometer”, turns the wrong way for radiation pressure (Maxwell refereed the paper)
- dark side hotter than shiny side → more pressure, Maxwell showed this is incorrect, just heat flow
- 1879 - Reynolds - submitted paper on “thermal transpiration”, flow of gas through porous plates with  $\Delta T$ , Maxwell refereed it, liked the ideas but not the math
- 1879 - Maxwell submitted “*On stresses in rarified gases arising from inequalities in temperature*”, crediting Reynolds, and then died
- 1881 - Reynolds paper was published
- 1901 - P. Lebedev, and E. Nichols & G. Hull, measure radiation pressure in better vacuums



“Light mill”, “solar radiometer”



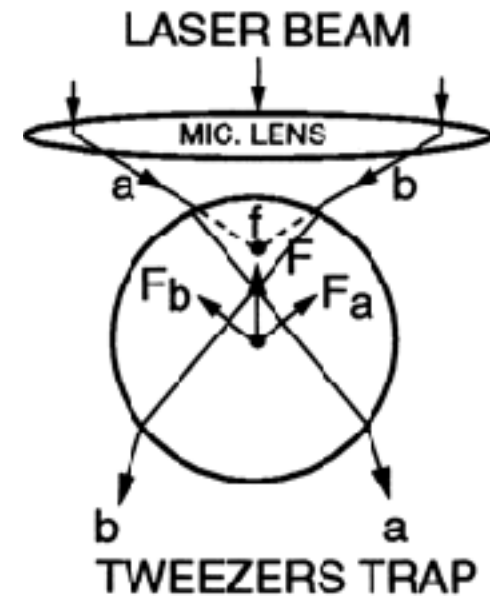
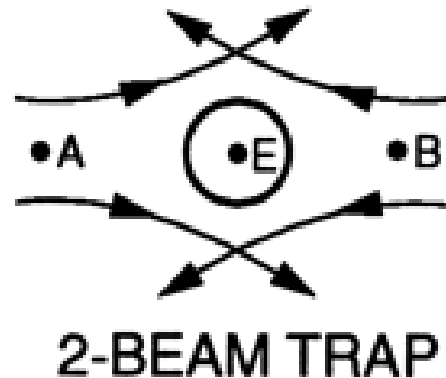
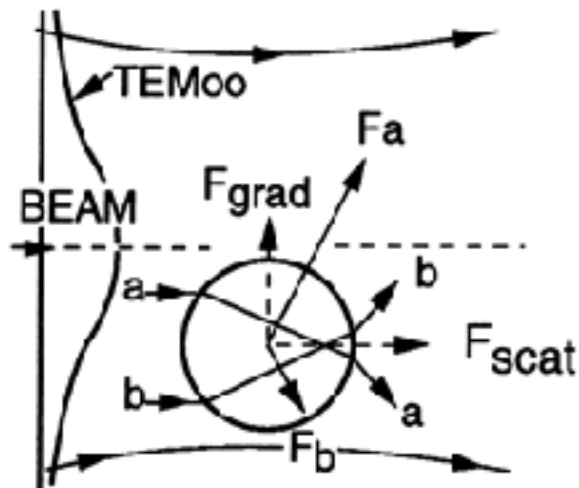
# Laser Trapping/Laser Tweezers

Ashkin, *et al*, at Bell Labs

- 1970: 2-d trapping of latex spheres in water
- 1970: 3d trapping in counter-propagating beams
- 1986: single beam 3-d trapping of atoms...
- 1987-9: **application to Biology begins...**

3 perspectives on trapping:

- force: refraction/ray tracing
- energy
- E field gradients



# All Optical Devices?

- Switching one light beam with another light beam
- Optical computing (perhaps for network)
- Rough comparison to other non-linear media:

$$n = n_0 + n'_2 |E|^2 \quad n'_2 \sim 1.5\chi^{(3)}/\epsilon_0 n_0$$

$$\Delta n/n_0 = (n'_2/n_0) |E|^2$$

$$n'_2/n_0 \sim 3.7 \times 10^{-23} \text{ m}^2/\text{V}^2, \text{ for SiO}_2$$

$$n'_2/n_0 \sim 3.6 \times 10^{-22} \text{ m}^2/\text{V}^2, \text{ for CS}_2$$

$$\Delta\theta = P_{\text{rad}} A/kl = (\epsilon/Y) |E|^2 \quad \text{optimally}$$

$$\epsilon/Y \sim 1.3 \times 10^{-22} \text{ m}^2/\text{V}^2, \text{ for Si/polystyrene}$$

- If enhance the effect and make devices smaller/faster gets interesting

# Radiation Pressure vs. Thermal effects

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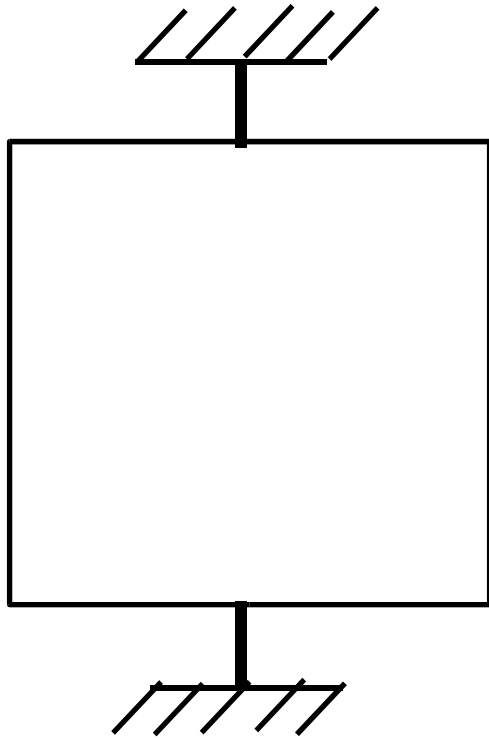
Why not just use thermal effects?

How to separate the effects?

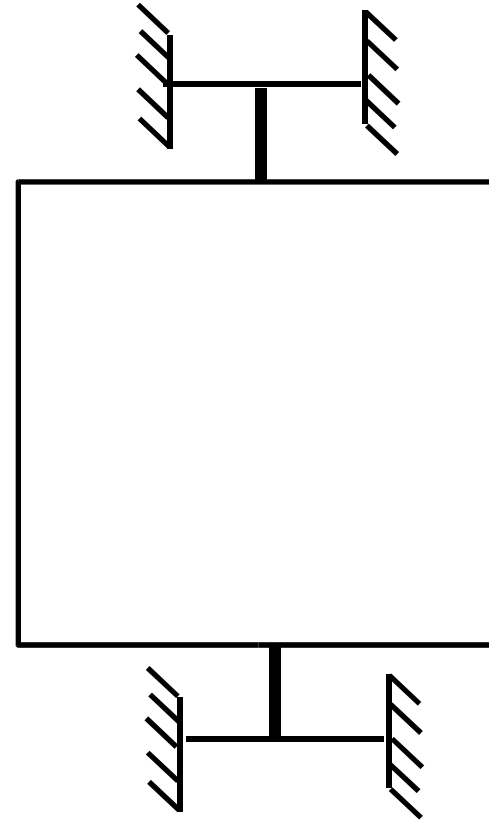
Big parasitic effect that raises a multitude of strategies/design issues

- reduce exposure of metals/semiconductors/absorbing materials
- pull heat away (by increasing coupling to outside)
- design to minimize thermal gradients
- choose wavelength/ materials correctly
- design to go with it (reduce coupling to mode of interest)
- work at frequencies above (thermal time constant)<sup>-1</sup>

# Reduce coupling to torsional mode?



Present design

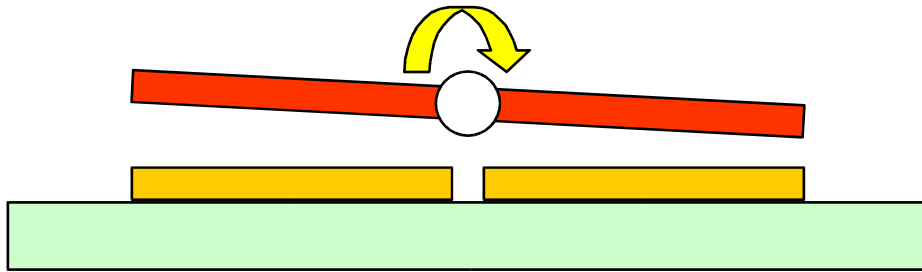


Improved design?

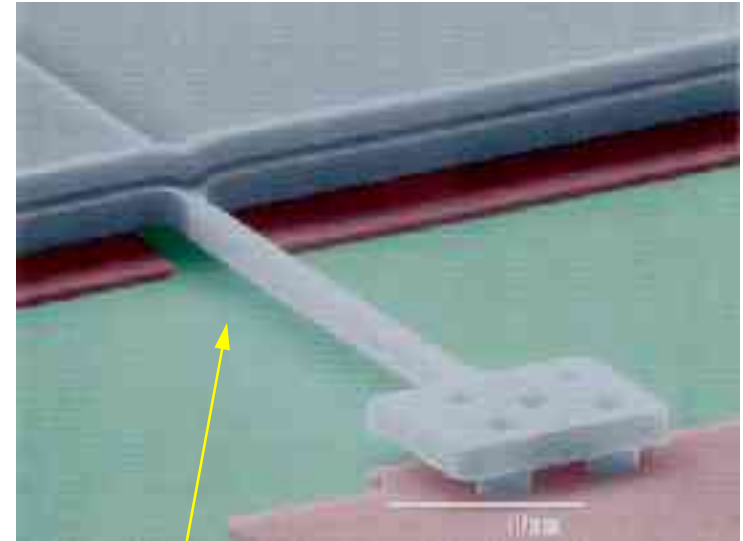
# Measurement System Outline

- MEMS device is actuator (and sensor)
- Glue dielectric sphere to MEMS device
  - to mimic laser tweezer experiments (functionally equivalent to a 1-d trap)
  - to minimize heating effects
- Optical design/layout
- HV chamber and vibration isolation
- Low-noise circuitry

# MEMS Force Sensor



|  |                            |
|--|----------------------------|
| $c = 2.1 \times 10^{-8} \text{ N-m}$     | $f_0 \sim 3500 \text{ Hz}$ |
| $I = 7.1 \times 10^{-17} \text{ kg m}^2$ | $Q \sim 25000$             |



Torsional rod  
cross section:  $1.5 \times 2 \mu\text{m}^2$

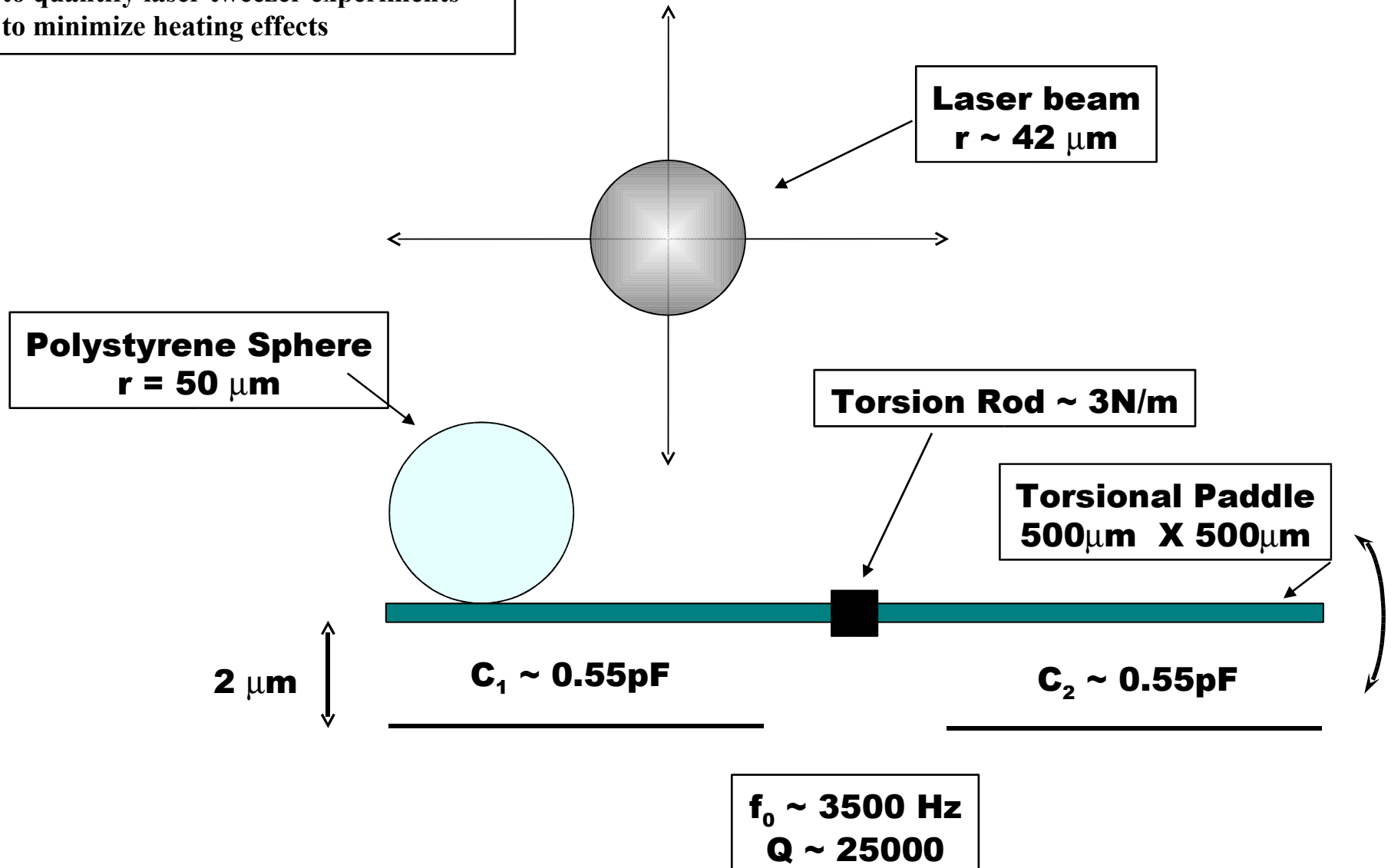


poly-Si plate:  
 $500 \mu\text{m} \times 500 \mu\text{m} \times 3.5 \mu\text{m}$

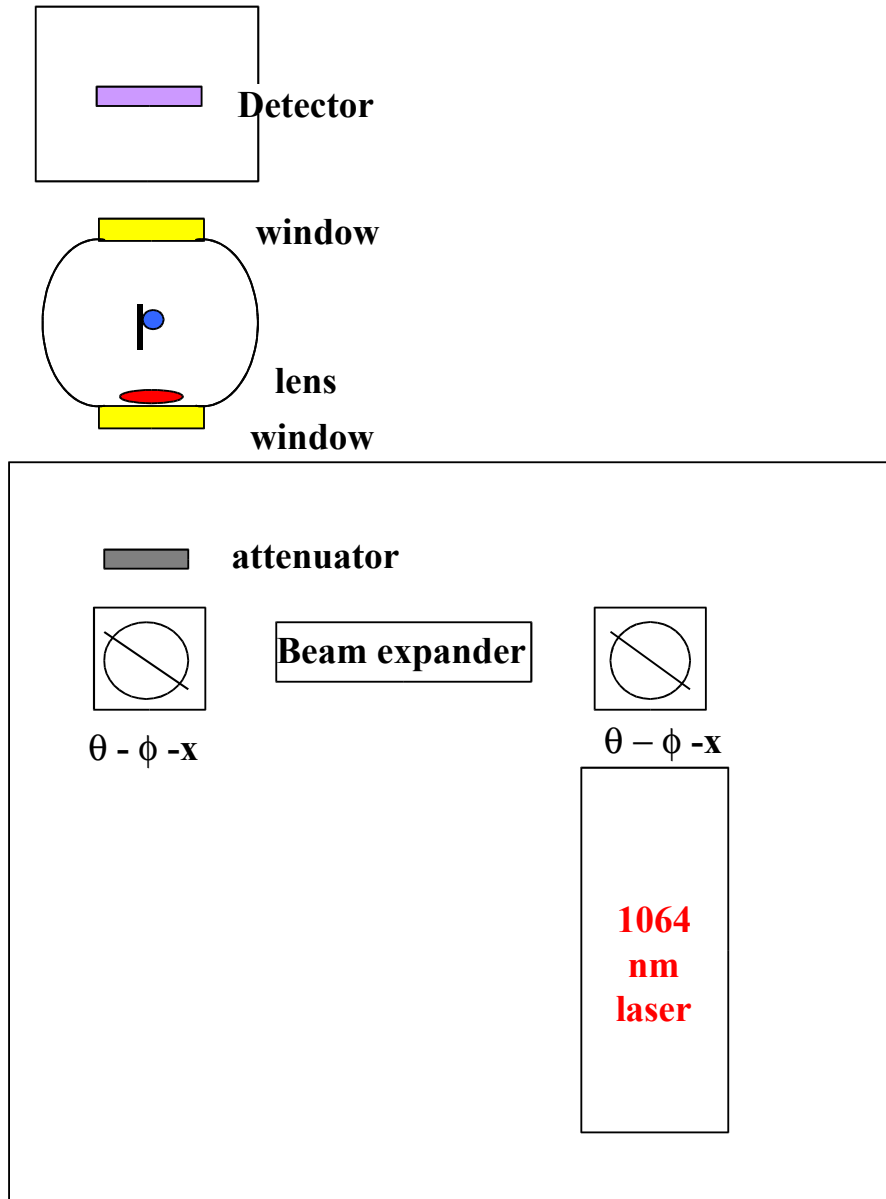
# Experimental Layout - Force sensor

Note: Use dielectric sphere intentionally:

- to quantify laser tweezer experiments
- to minimize heating effects



# Experimental Layout - Optics



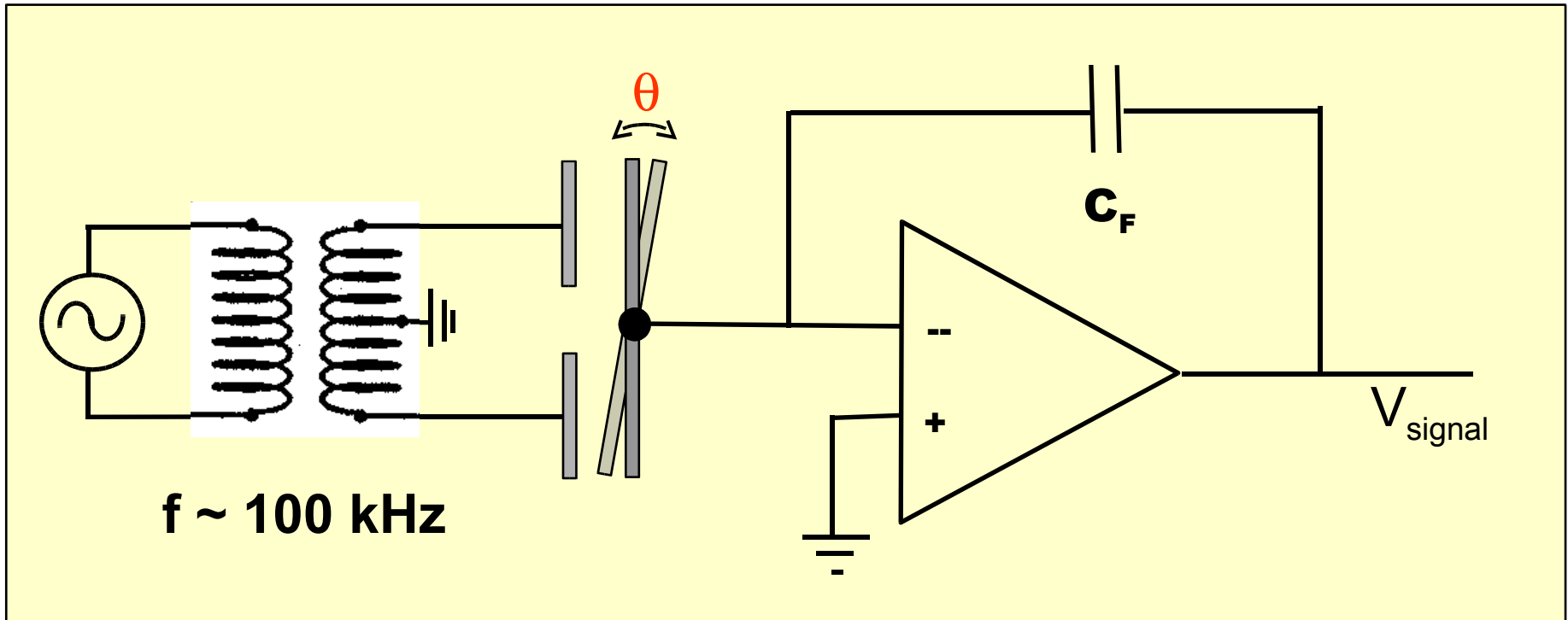
**+ HV system  
( $\sim 10^{-9}$  Torr)  
on vibration  
isolation table**



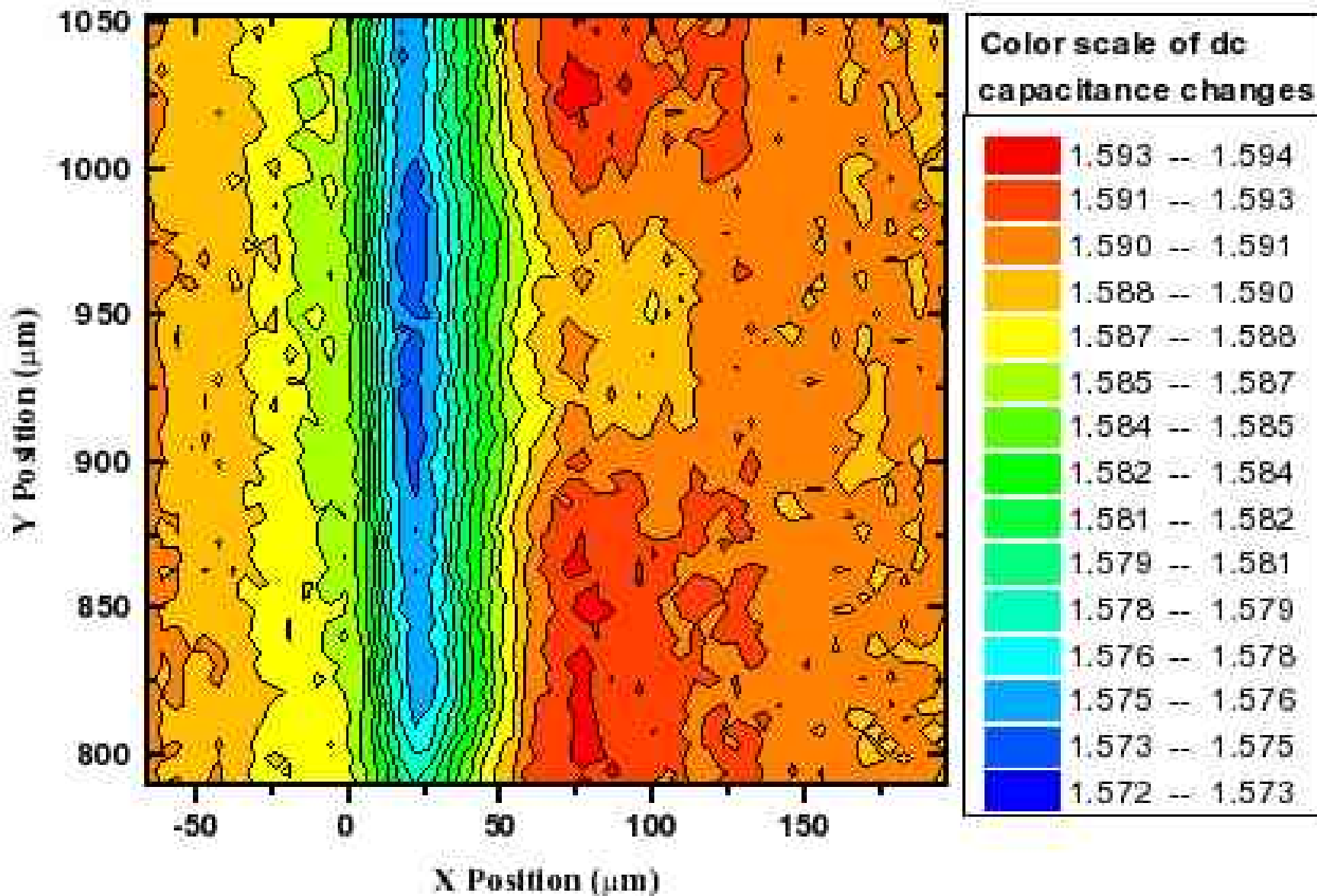
# Circuitry for dc Detection

Capacitive detection of torsional motion

For small  $\theta$ ,  
 $V_{\text{signal}} \propto \Delta C$   
 $\propto \theta$   
 $\propto \Delta F$



# dc Capacitance Shift



- Thermal noise of detector from  $e_n$  of input transistor; flat *vs.* frequency
- Thermal noise of oscillator peaked at resonance:

$$f_n \sim (4k_B T k Q / \omega_0)^{1/2}$$

- But signal increases by  $Q$  at resonance

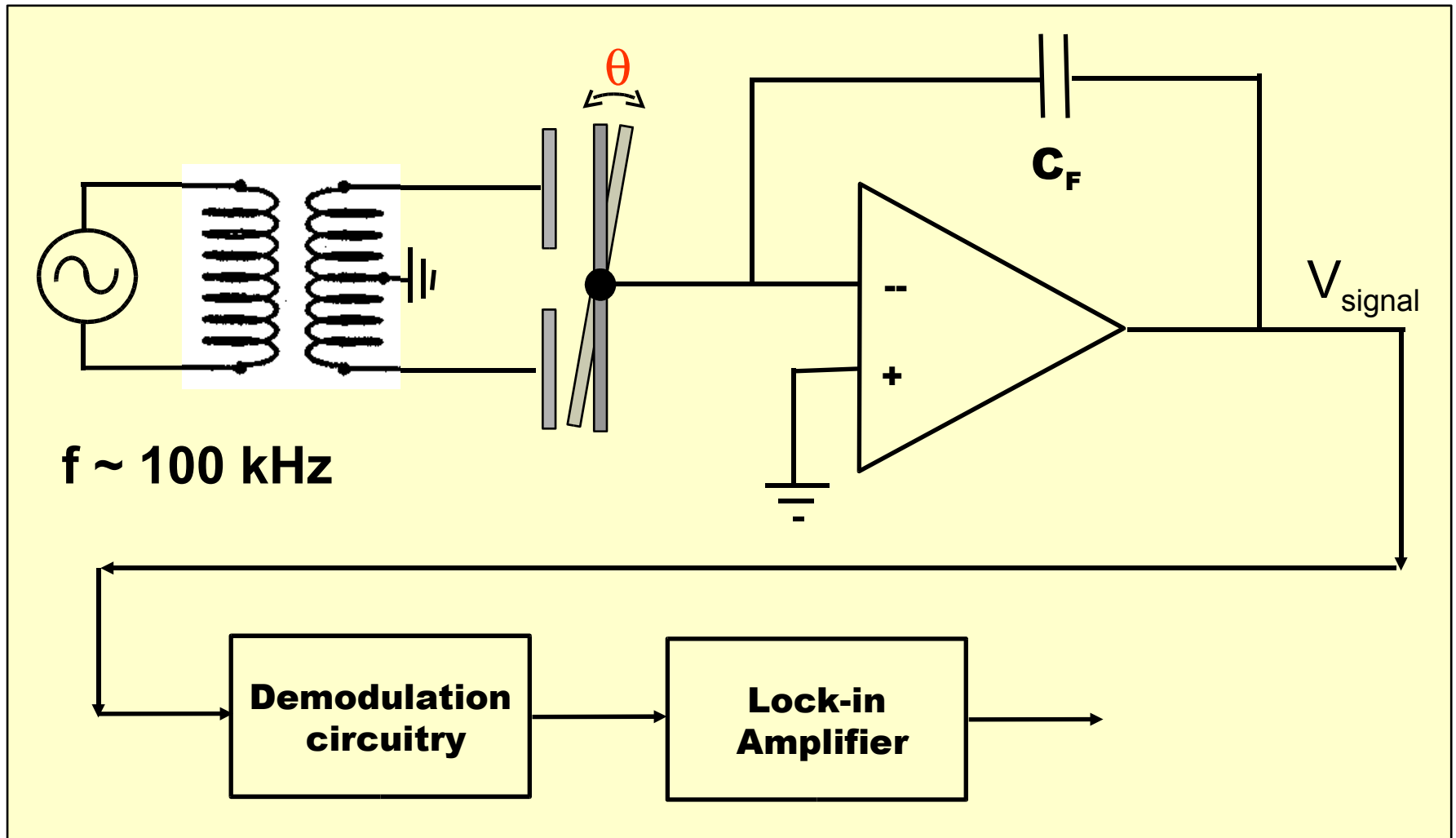
$$f_n' \sim (4k_B T k / Q \omega_0)^{1/2}$$

- $\therefore$  Signal to noise generally improves at resonance
- Want low  $k$ , high  $\omega_0$ , high  $Q$ :

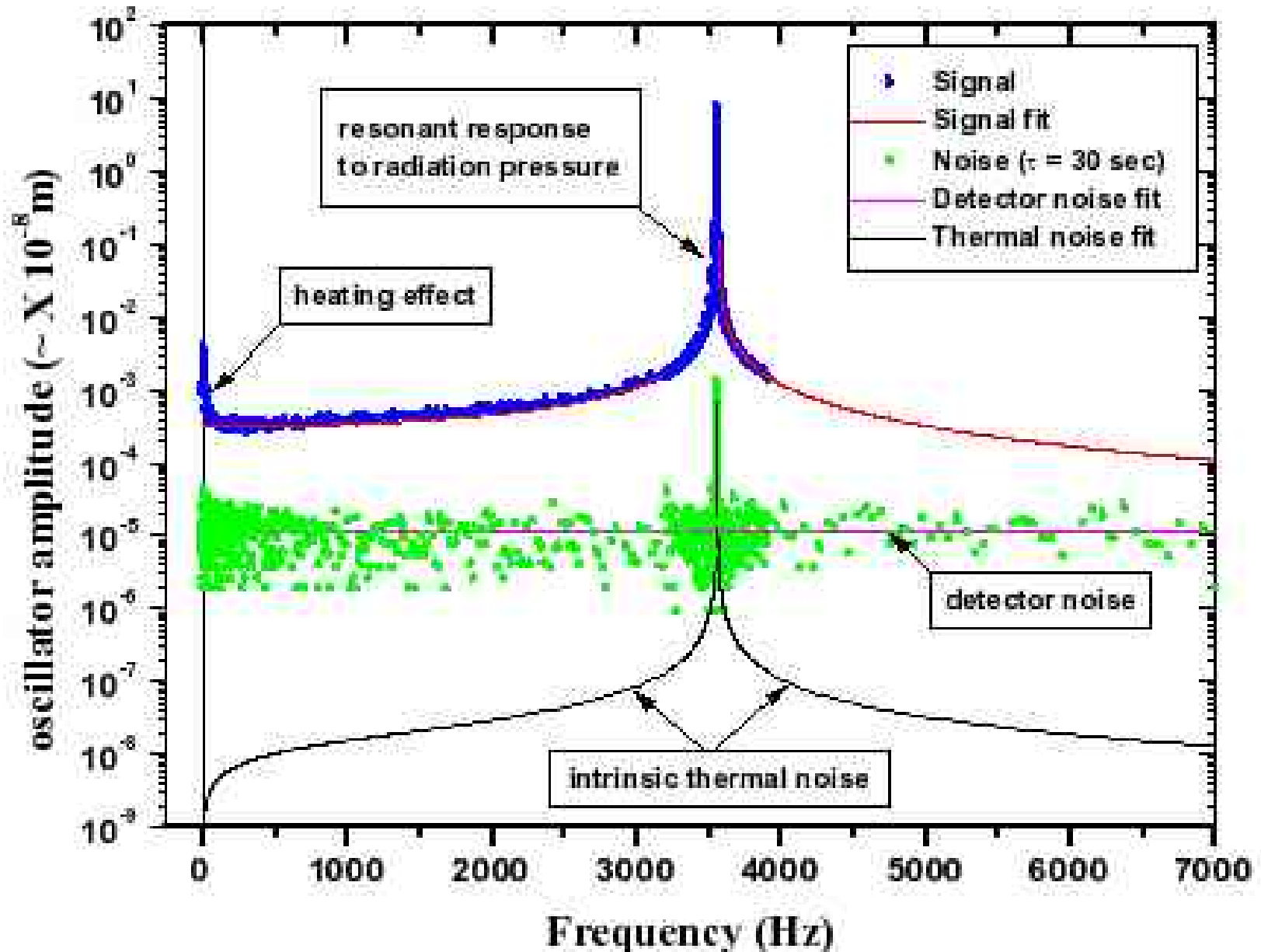
ideal direction for MEMS

# Circuitry for ac Detection

Can drive the oscillator electrically or optically and use demodulation circuitry to measure ac components with  $\sim 10$  kHz BW

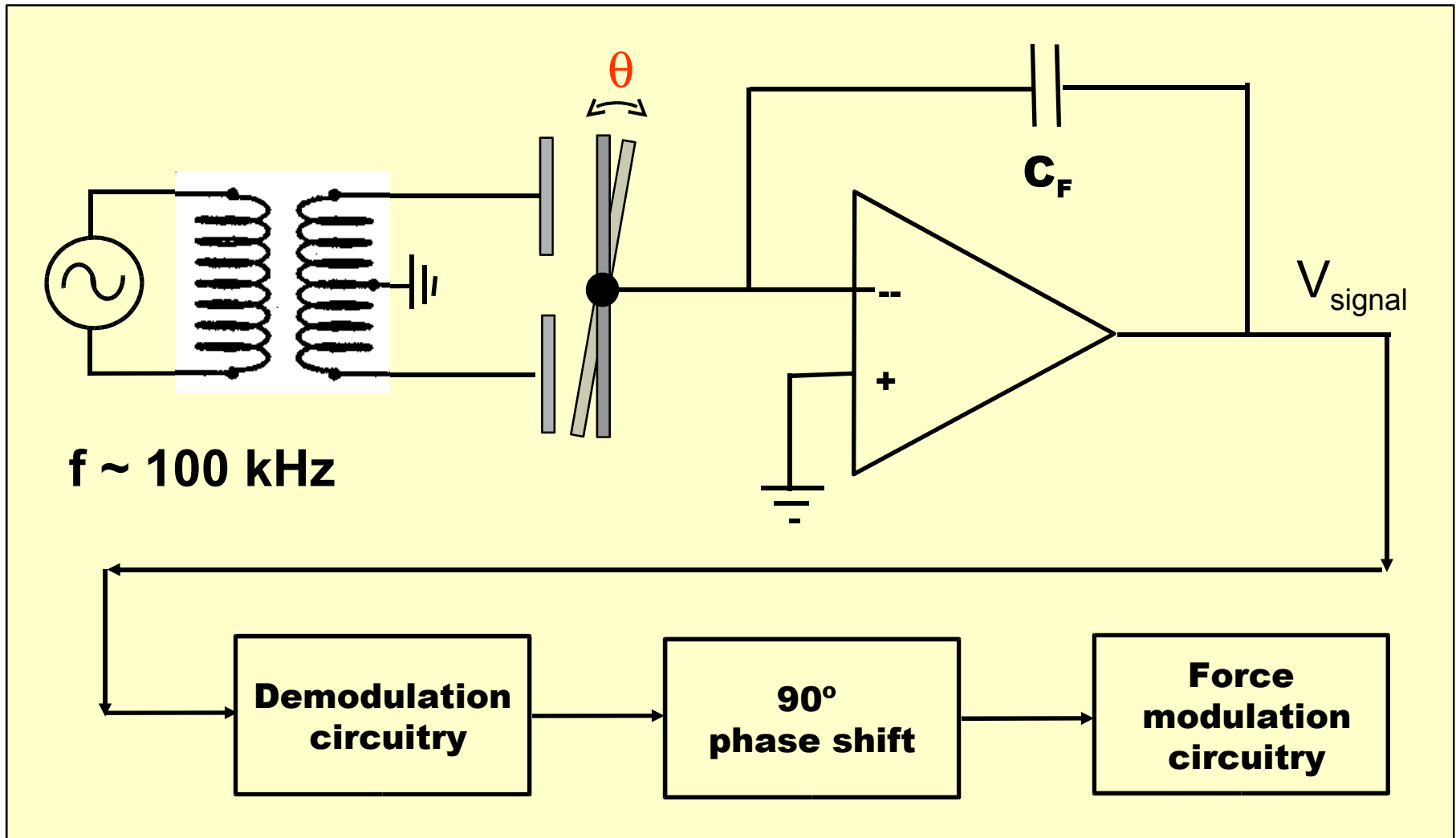


# Frequency Dependence

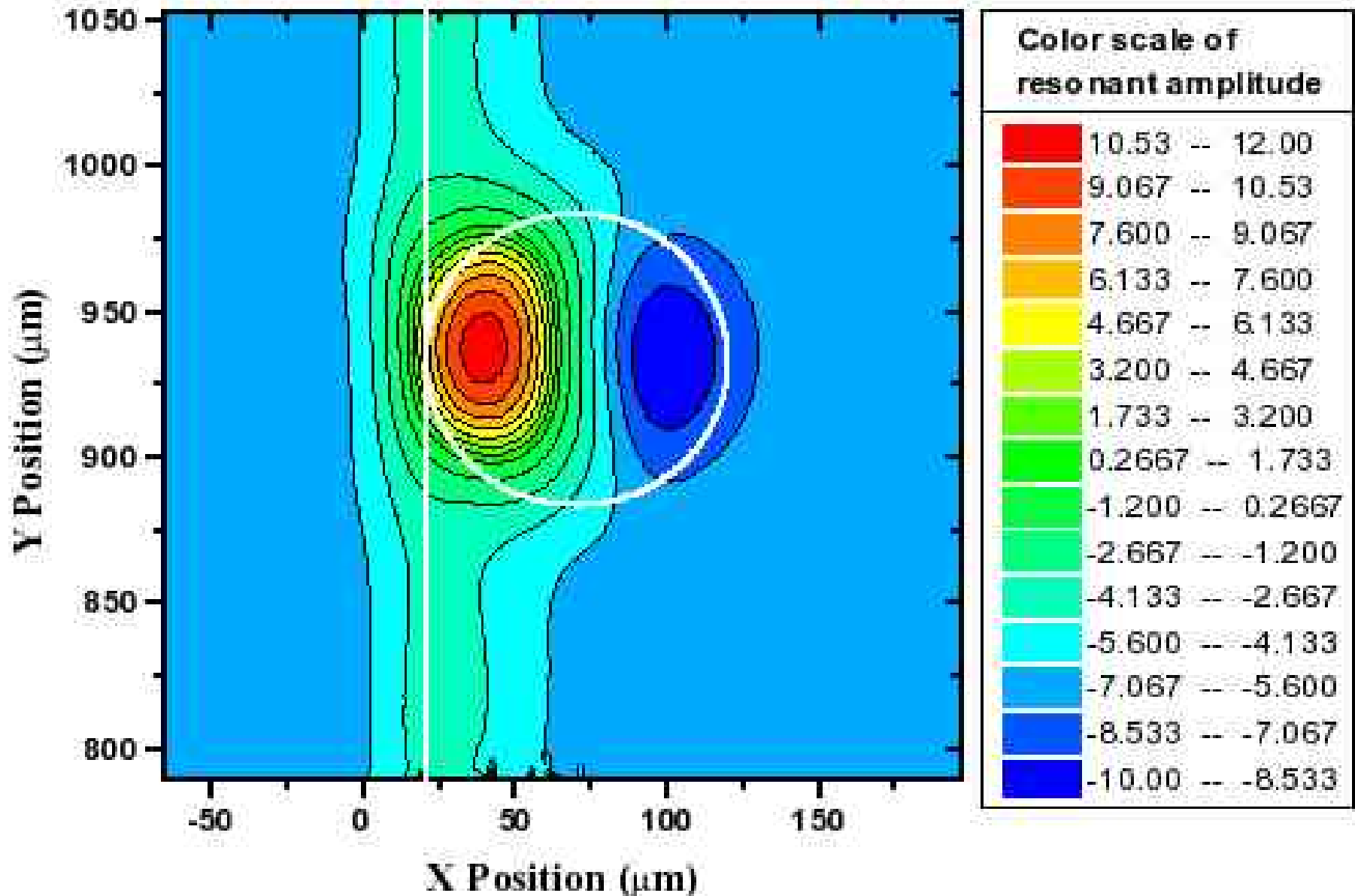


# Circuitry for Resonant Detection

Modulate force at resonant frequency of torsional oscillator

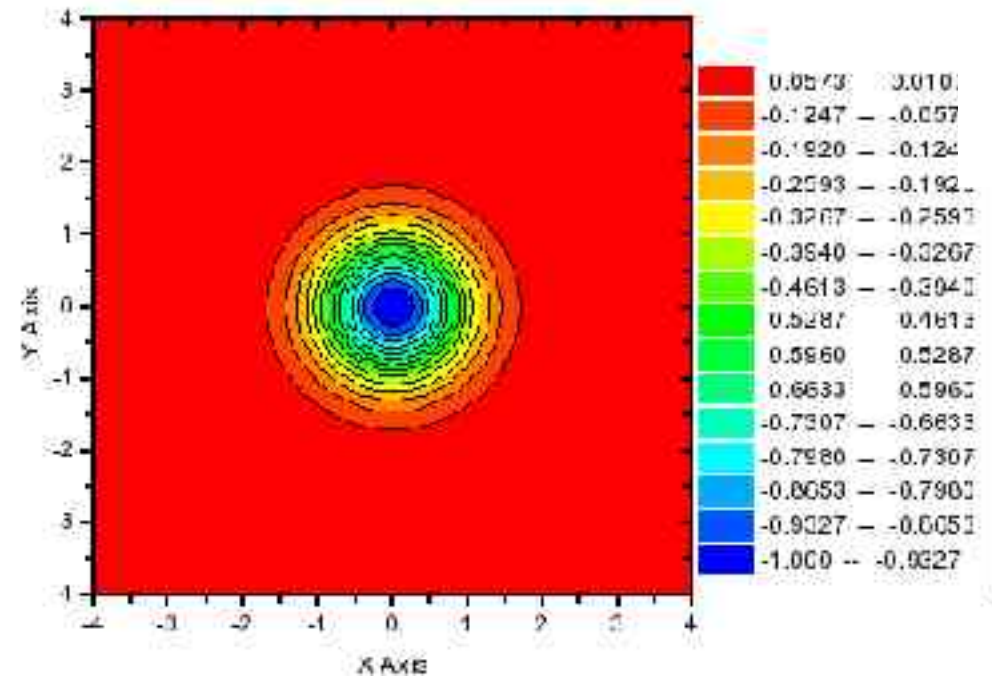
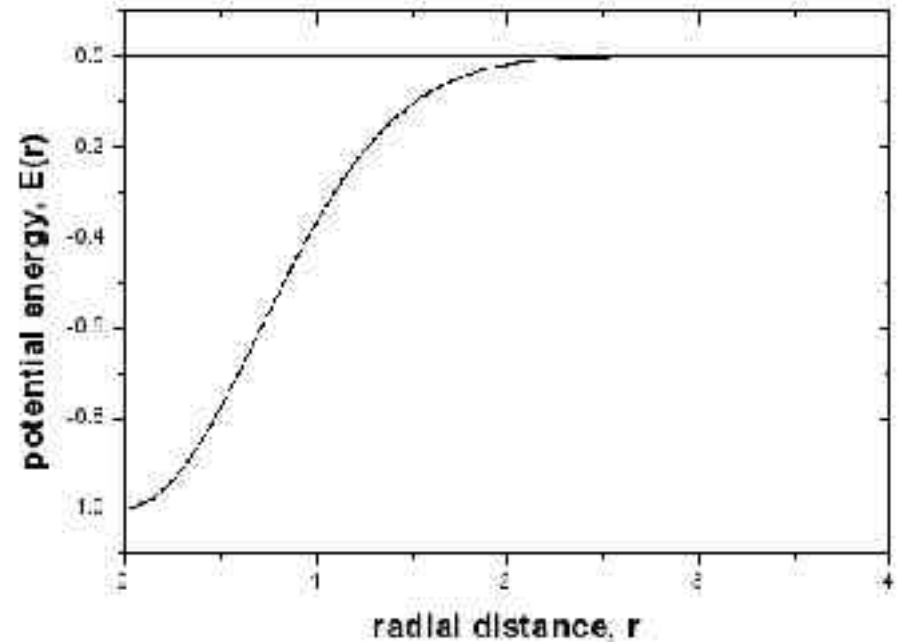


# Resonant Amplitude



# Potential Energy

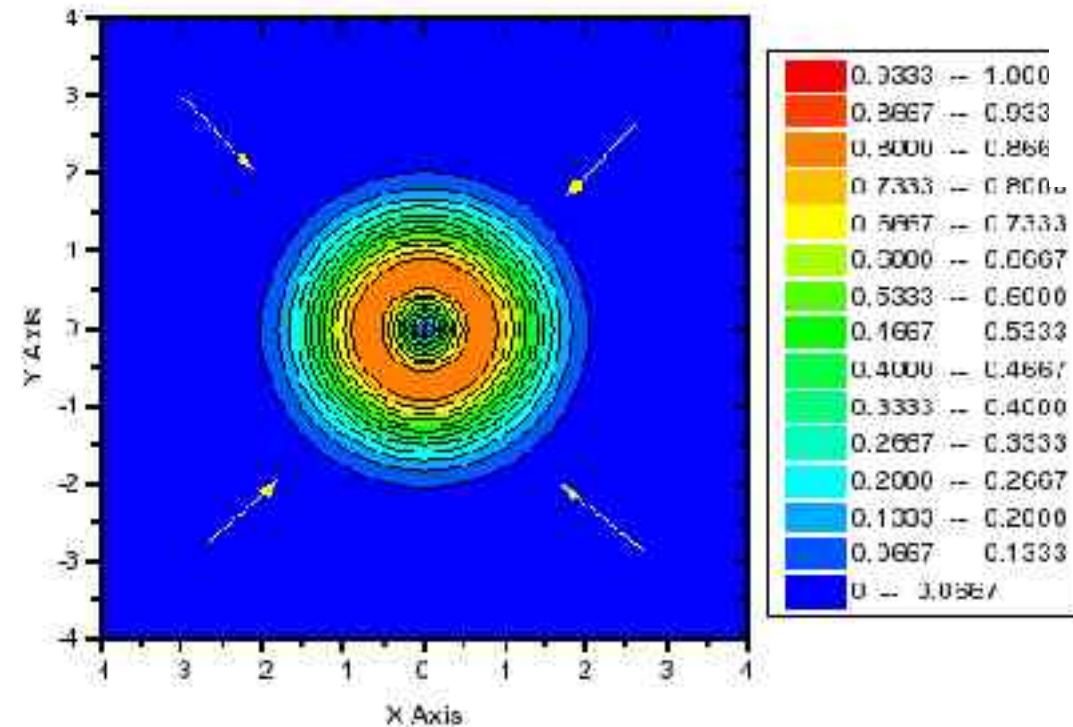
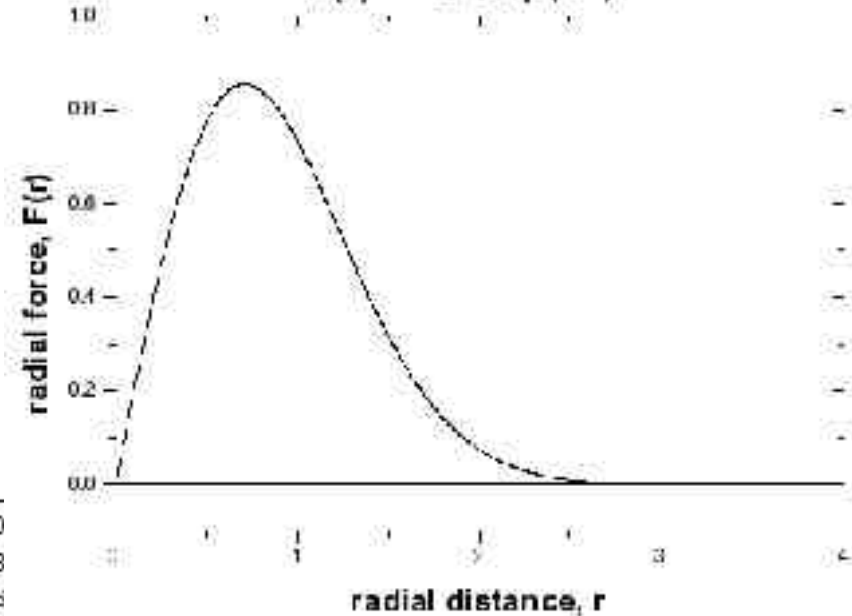
$$E(r) = -\exp(-r^2)$$



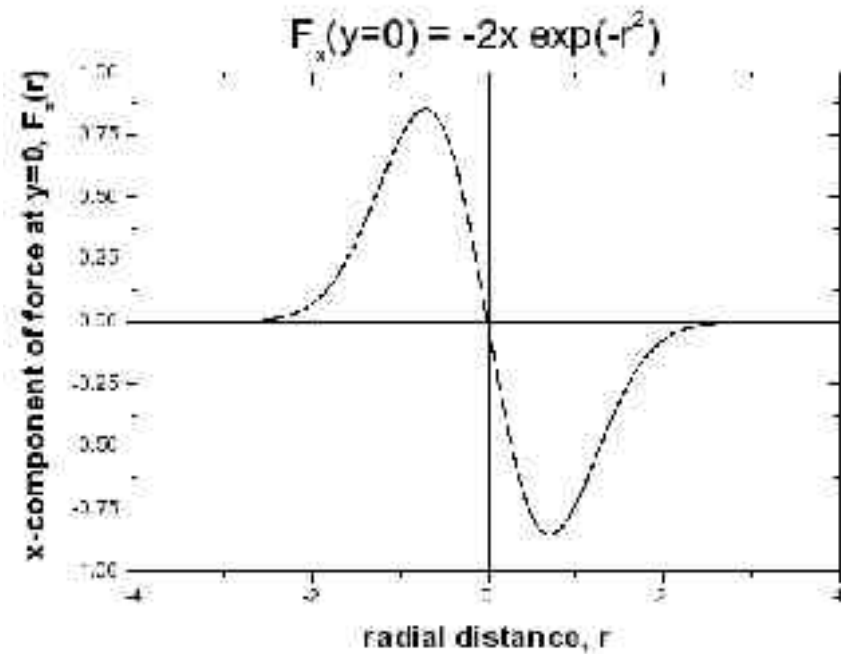
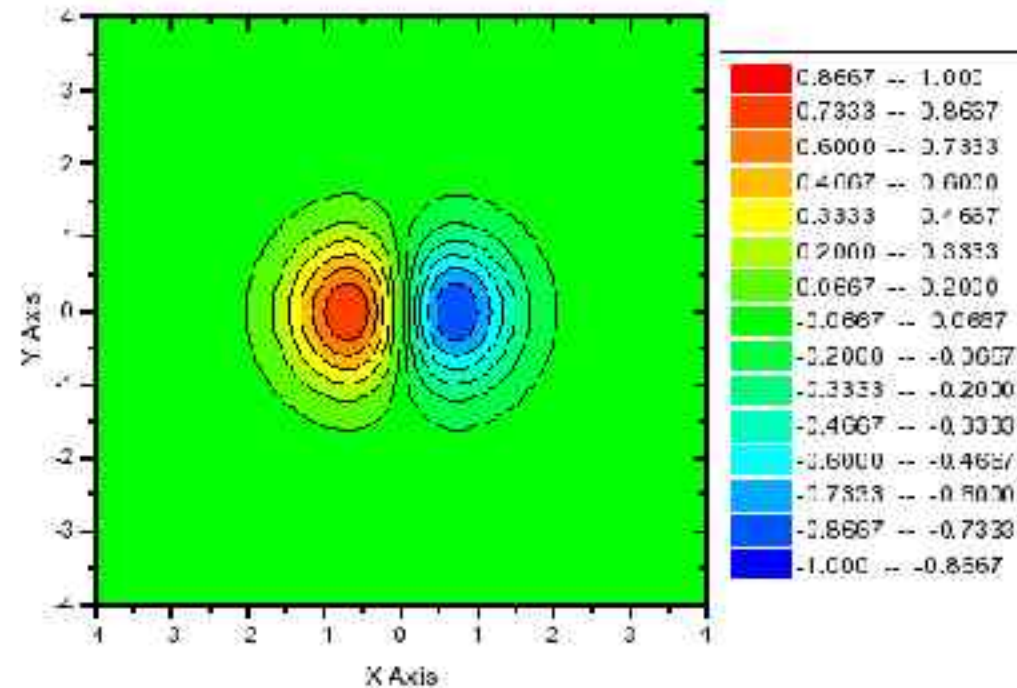


# Radial Force

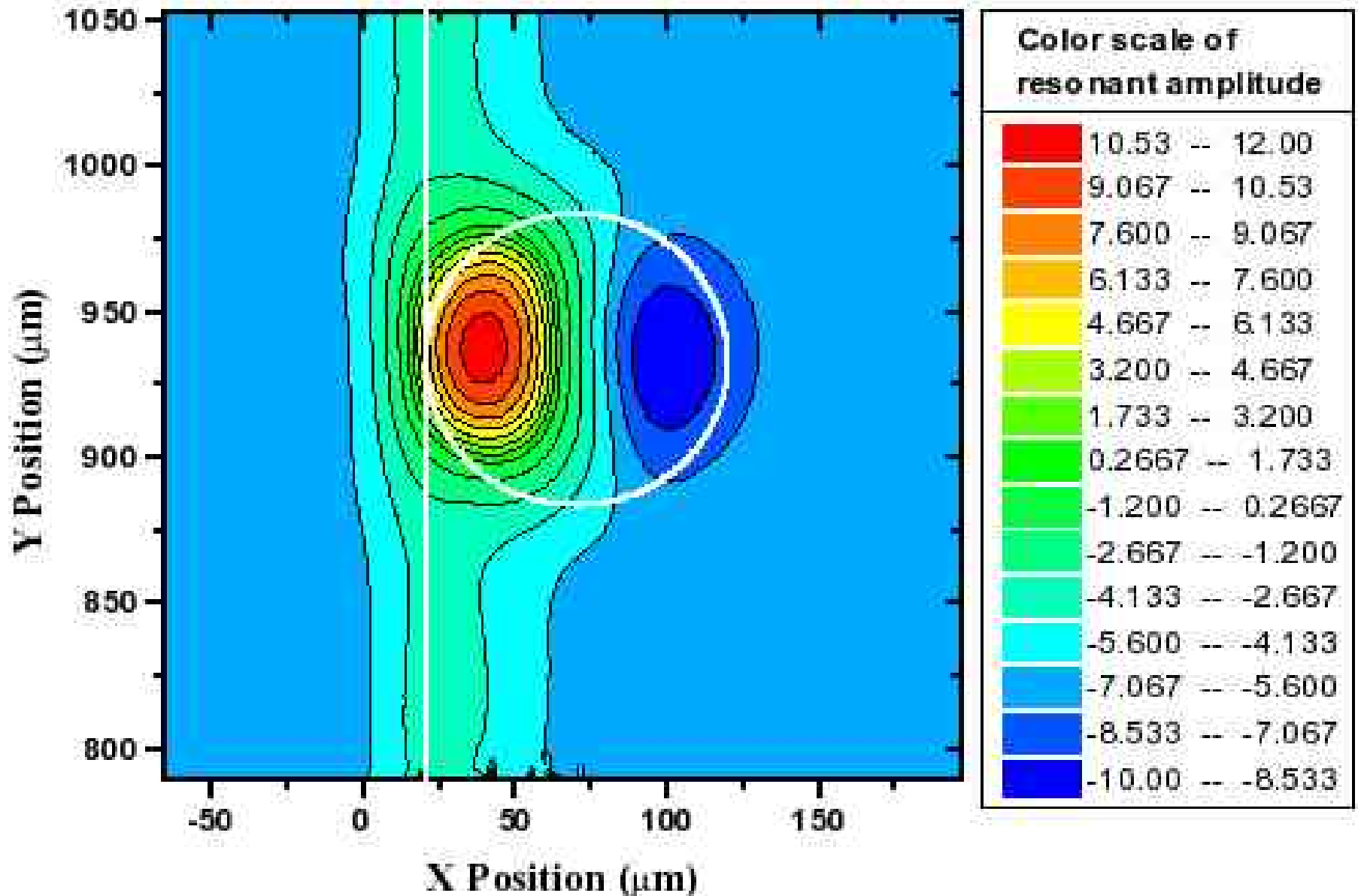
$$F(r) = -2r \exp(-r^2)$$



# x-component of Force



# Resonant Amplitude



# Polarization Dependence and Anisotropy Effects

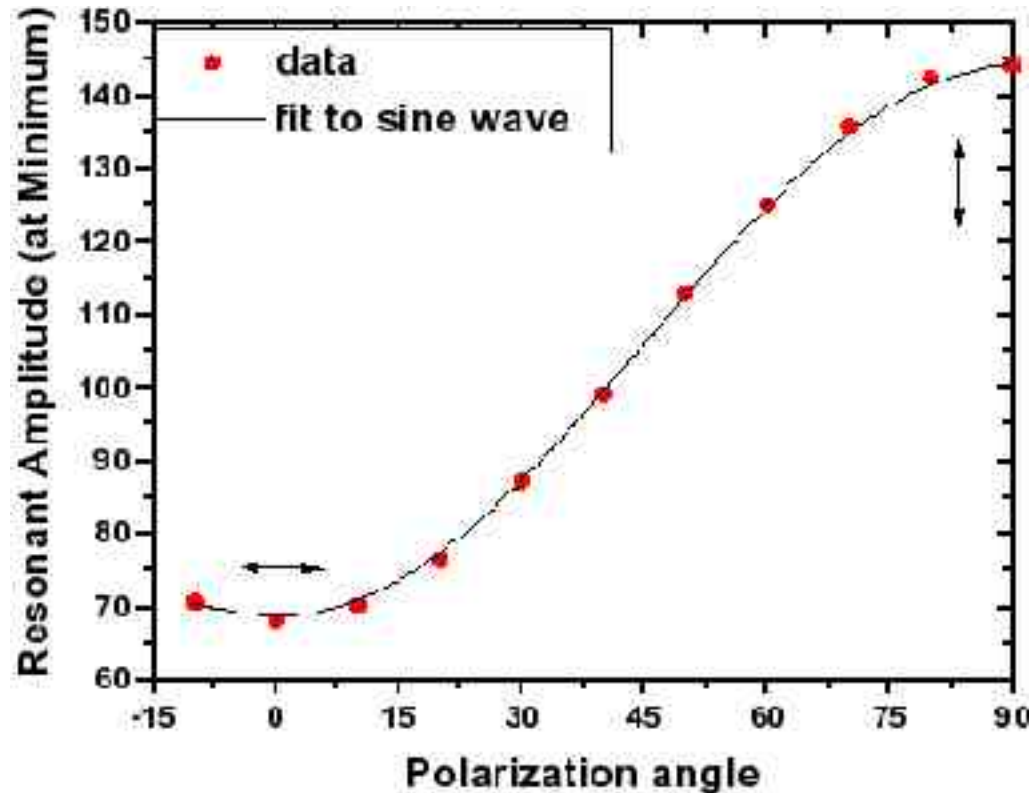
Total force,  $F$ , on a piece of polarized dielectric:

$$F = \int (P \cdot \nabla) E \, dV$$

For a *linear and isotropic* dielectric:

$$\mathbf{P} = \epsilon_0 \chi \mathbf{E}$$

$$(\mathbf{P} \cdot \nabla) \mathbf{E} = \frac{1}{2} \epsilon_0 \chi \nabla (E^2)$$



If  $\mathbf{P} \neq \epsilon_0 \chi \mathbf{E}$ , then force is not radially symmetric

Related to torques observed on asymmetric objects

# Quantitative Results

- Thermal time constant  $\sim 35$  ms  
conduction through rods + some radiative coupling
- 4 methods for calibrating optical force: detection electronics, electrical drive, thermal noise of oscillator (equivalent to method used for tweezers), detector noise
- Displacement noise:  $x_n = 2.0$  pm/Hz<sup>1/2</sup> off resonance
- Force noise:  $f_n = 6.0$  pN/Hz<sup>1/2</sup> off resonance
- Equivalent noise:  $f_n' = 0.017$  pN/Hz<sup>1/2</sup> on resonance
- Displacement  $\sim 4.4$  pm at dc, 110 nm at resonance, 3 mW
- Force experimentally observed:  
 $F = 0.26$  pN/mW  $\pm$  many systematic checks
- Force theoretically expected:  
 $F \sim 0.06/c = 0.20$  pN/mW  $\pm$  detailed calculations
- Anisotropy ( $\sim 3:1$ ), some idea why, interesting in itself

# Conclusions

Convincing evidence of radiation pressure on a dielectric sphere:

- numbers are reasonable
- separation of thermal effects from radiation pressure by examining the frequency dependence
- spatial variation is reasonable

See anisotropy/polarization effects in present device

Better S/N by working at resonance ( $\sim 0.017 \text{ pN/Hz}^{1/2}$ )

Significant actuation of the MEMS device (110 nm)

With enhancements and optimization  $\swarrow$  potential for interesting all-optical devices